1. In the below code, written in intel syntax, how many arguments does this subroutine have?

```
push ebp
mov ebp, esp
sub esp. 8
mov DWORD PTR [ebp-4], ecx
mov DWORD PTR [ebp-8], edx
mov edx, DWORD PTR [ebp-4]
mov eax, DWORD PTR [ebp-8]
add edx. eax
mov eax, DWORD PTR [ebp+8]
add edx, eax
mov eax, DWORD PTR [ebp+12]
add edx, eax
mov eax, DWORD PTR [ebp+16]
add eax, edx
leave
ret 12
```

2. Using an assembler show and contrast the differences between the following code once it is compiled. Do optimizations change the ways the constructs work? Include source code and assembly.

- The c++ post-fix increment (i++) compares to i = i + 1.
- The ternary operator compared to if and else.
- The while, for, and do while loops.

3. In the below code in AT&T Syntax, In the below basic block of assembly, what value is returned by this subroutine when the last instruction executes.

```
push %ebp
mov %esp, %ebp
mov 8(%ebp),%ecx
mov12(%ebp),%eax
sub %eax, %ecx
mov %ecx, %eax
pop %ebp
Ret
```

4. In the below code, How many arguments does function Five and function Six have?

Z4fiveiii:	_Z3sixiii:
push ebp	push ebp
mov ebp, esp	mov ebp, esp
sub esp, 16	push DWORD PTR [ebp+12]
mov eax, DWORD PTR [ebp+8]	push DWORD PTR [ebp+8]
sub eax, DWORD PTR [ebp+16]	push DWORD PTR [ebp+16]
mov DWORD PTR [ebp-4], eax	call _Z4fiveiii
mov eax, DWORD PTR [ebp+12]	add esp, 12
add DWORD PTR [ebp-4], eax	leave
mov ecx, DWORD PTR [ebp-4]	ret
mov edx, 1431655766	
mov eax, ecx	
imul edx	
mov eax, ecx	
sar eax, 31	
sub edx, eax	
mov eax, edx	
mov DWORD PTR [ebp-4], eax	
mov eax, DWORD PTR [ebp-4]	
leave	
ret	

5. Using the same Assembly code as question (4) What is accomplished logically by the mangled "six" function.

6. Given the instruction: cmp a, b;

Give values for a and b to set all possible combinations of EFLAGS that can be set from a cmp instruction. Construct a table with the values of a and b and what flags were set.

7. Calculate the value of the eax register when the main function returns.

main: push ebp mov ebp, esp sub esp, 32 mov DWORD PTR [ebp-24], 123434 mov DWORD PTR [ebp-20], 9000 mov DWORD PTR [ebp-16], 2243244 mov DWORD PTR [ebp-12], 34250234 mov DWORD PTR [ebp-8], 234234 mov DWORD PTR [ebp-4], 0 lea eax, [ebp-24] push eax call _Z1fPi add esp, 4 cwde leave ret	_Z1fPi: push ebp mov ebp, esp sub esp, 16 mov DWORD PTR [ebp-8], 0 jmp .L2 .L3: mov eax, DWORD PTR [ebp-8] lea edx, [0+eax*4] mov eax, DWORD PTR [ebp+8] add eax, edx mov eax, DWORD PTR [ebp+8] add eax, edx mov WORD PTR [ebp-2], ax add DWORD PTR [ebp-8], 1 .L2: mov eax, DWORD PTR [ebp-8] lea edx, [0+eax*4] mov eax, DWORD PTR [ebp+8] add eax, edx mov eax, DWORD PTR [ebp+8] add eax, edx
	.L2: mov eax, DWORD PTR [ebp-8] lea edx, [0+eax*4] mov eax, DWORD PTR [ebp+8] add eax, edx mov eax, DWORD PTR [eax] test eax, eax jne .L3 movzx eax, WORD PTR [ebp-2] leave ret

8. If the following program was ran with arguments 10 and 9, what would be the return value?

_Z1fPiS_:	main:
push ebp	lea ecx, [esp+4]
mov ebp, esp	and esp, -16
sub esp, 16	push DWORD PTR [ecx-4]
mov DWORD PTR [ebp-4], 9000	push ebp
mov eax, DWORD PTR [ebp+12]	mov ebp, esp
mov eax, DWORD PTR [eax]	push ebx
imul edx, eax, 9000	push ecx
mov eax, DWORD PTR [ebp+8]	sub esp, 16
mov DWORD PTR [eax], edx	mov ebx, ecx
mov eax, DWORD PTR [ebp+8]	mov eax, DWORD PTR [ebx+4]
mov eax, DWORD PTR [eax]	add eax, 4
mov edx, 9000	mov eax, DWORD PTR [eax]
sub edx, eax	sub esp, 12
mov eax, DWORD PTR [ebp+12]	push eax
mov DWORD PTR [eax], edx	call atoi
leave	add esp, 16
ret	mov DWORD PTR [ebp-12], eax
	mov eax, DWORD PTR [ebx+4]
	add eax, 8
	mov eax, DWORD PTR [eax]
	sub esp, 12
	push eax
	call atoi
	add esp, 16
	mov DWORD PTR [ebp-16], eax
	sub esp, 8
	lea eax, [ebp-16]
	push eax
	lea eax, [ebp-12]
	push eax
	call Z1fPiS
	add esp. 16
	mov edx, DWORD PTR [ebp-12]
	mov eax, DWORD PTR [ebp-16]
	add eax edx
	lea esp [ebp-8]
	DOD ecx
	pop ebx
	pop ebp
	lea esp [ecv_4]
	rot

Graduate Students:

Produce an assembly file (-s in gcc and .s file) which computes the 13th fibonacci number consisting of no registers. The filed turned in should be compilable assembly code using standard g++ and each instruction of the assembly file should not contain standard process registers (EAX, EBX, ECX, EDX, ESI, EDI) The exception is you are allowed to use EBP and ESP in this program. You should not use the smaller size aliases of these registers i.e. You should not use AL in place of EAX,.